

Chapter 13 Vibrations and Waves

- Hooke's Law $F_s = -kx$

F_s force of the spring (F_s opposes F applied to stretch/compress spring) (N)

k spring constant (N/m)

x amount of stretch/compression (m)

sign convention/frame of reference: right +, left –

force is directly proportional to the displacement (x)---linear relationship

graphically represented by a line, with slope = k value

- Simple Harmonic Motion-if an object vibrates according to Hooke's Law; ex. object suspended from a vertical spring.

Amplitude (variable A in meters)-maximum amount of displacement from equilibrium position

Period (variable T , tau, in seconds)-the time for one complete cycle, vibration, wave, oscillation, etc.

Frequency (variable f in $1/s$, s^{-1} or Hz)-the number of cycles/vibrations/waves in one second

Find the spring constant in lab: use mass suspended vertically from spring, set $F=mg$, measure spring displacement, collect about 5 sets of data points, graph to a best fit line. The slope of the line corresponds to the k value.

- Elastic Potential Energy

U_s potential energy due to a spring measured in Joules (in class we used PE_s , AP uses U_s)

$$U_s = \frac{1}{2}kx^2 \quad U \text{ in Joules (J), } k \text{ in (N/m), } x \text{ in (m)}$$

Conservation of Energy

Initial Energy = Final Energy

$$\frac{1}{2}kx_i^2 + \frac{1}{2}mv_i^2 + mgh_i = \frac{1}{2}kx_f^2 + \frac{1}{2}mv_f^2 + mgh_f$$

If all motion is horizontal, ignore mgh on both sides

Stored up spring energy turns into velocity of object once released from rest

$$\frac{1}{2}kx_i^2 = \frac{1}{2}mv_f^2$$

- Velocity as a function of position

$$V = \pm \sqrt{(k/m)(A^2 - x^2)}$$

Period and Frequency

$$T = 2\pi \sqrt{m/k} \quad 2\pi f = \sqrt{k/m} \quad f = 1/T \quad T = 1/f$$

- Position, velocity, and acceleration as a function of time

$$X = A \cos(2\pi ft)$$

A is amplitude in m; f is frequency in Hz; t is time in seconds; x is position in m

- Motion of a pendulum

$$T = 2\pi \sqrt{L/g}$$

L is length of pendulum in m; g is 9.8 m/s² on earth

Types of waves-longitudinal or transverse

Wave speed or $v = f\lambda$ v in m/s, f in 1/s or Hz, and λ (lambda) is wavelength in m

- Speed of waves in a spring

$$v = \sqrt{F / \mu}$$

v in m/s, F or Tension in Newtons (usually mg), and μ is mass per unit length of string in kg/m

The more tension in the spring, the less freedom for a wave to travel through it.

Constructive Interference- when waves *in-phase* (having same f and A) combine, the resultant wave has same f, but twice the A.

Destructive Interference-when waves are 180° out of phase, the resultant wave is complete cancellation.

Superposition principle-then two waves combine, the resultant can be found by adding the individual waves together point by point.